The combinatorics of polytopes and the simplex algorithm Gil Kalai Institute of Mathematics

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Let P be a d-polyhedron with n facets, i.e. P is the set of solutions of n linear inequalities with d variables. The vertices (extreme points) and edges (1-dimensional faces) of P form a graph denoted by G(P). This graph is of great interest in the combinatorial theory of polytopes and in the theory of linear programming. The simplex algorithm finds the maximum value of a linear (objective) function on P by moving from vertex to adjacent vertex in the graph of P.

An example to always have in mind is: P is the *d*-dimensional cube defined by the 2*d* inequalities $0 \le x_i \le 1$. P has 2*d* facets and 2^d vertices all 0-1 vectors. Two vertices are adjacent in the graph of P if they differs in one coordinate.

We will discuss the following open problems (all of them are wide open, but for 1-3 there are some partial results):

- 1. What is the maximal diameter of the graph of a d-dimensional polyhedra with n facets?
- 2. Is there a pivot rule for the simplex algorithm which is good in the worst case?
- 3. How good expanders are graphs of polytopes?
- 4. How hard is it to find a random vertex of a polyhedron?
- 5. How hard is it to approximate the number of vertices of a d-polyhedra with n facets?

Some relevant references:

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